

Physics 2414
Final Exam

Instructions: Please sit in the indicated seat. Write your name, student ID, exam version and discussion section on your answer sheet and put all of your answers on the answer sheet. Hand in the answer sheet when you are done.

Area of Sphere = $4\pi r^2$
 $g = 9.8 \text{ m/s}^2$
 Volume of Sphere = $\frac{4}{3}\pi r^3$
 $G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$
 $r_{\text{earth}} = 6.38 \times 10^6 \text{ m}$
 $m_{\text{earth}} = 5.98 \times 10^{24} \text{ kg}$

$\vec{v}_{av} = \frac{\Delta \vec{x}}{\Delta t}$
 $\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{x}}{\Delta t}$
 $\vec{a}_{av} = \frac{\Delta \vec{v}}{\Delta t}$
 $\vec{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t}$
 $\Delta v_x = v_x - v_{ox} = a_x t$
 $v_{av,x} = \frac{v_{ox} + v_x}{2}$
 $\Delta x = x - x_o = v_{ox} t + \frac{1}{2} a_x t^2$
 $v_x^2 - v_{ox}^2 = 2a_x \Delta x$

4 Kinematic equations :

- 1) $v = v_o + at$
- 2) $x = x_o + \frac{1}{2}(v + v_o)t$
- 3) $x = x_o + v_o t + \frac{1}{2}at^2$
- 4) $v^2 = v_o^2 + 2a(x - x_o)$

Kinematic equations for an object moving in two dimensions with constant acceleration along the y-axis and $t_o = 0$.

$v_x = v_{ox}$
 $x - x_o = v_{ox} t$
 $v_y = v_{oy} + a_y t$
 $\Delta y = v_{av,y} t$
 $v_{av,y} = \frac{1}{2}(v_{oy} + v_y)$
 $y - y_o = v_{oy} t + \frac{1}{2}a_y t^2$
 $v_y^2 - v_{oy}^2 = 2a_y \Delta y$

$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$
 $\cos \theta = \frac{\text{adjacent}}{\text{hypotenuse}}$
 $\tan \theta = \frac{\text{opposite}}{\text{adjacent}}$

$F = \frac{Gm_1 m_2}{r^2}$

$f_s \leq \mu_s F_N$
 $f_k = \mu_k F_N$
 $F = kx$
 $\Sigma F_x = ma_x$
 $\Sigma F_y = ma_y$
 $\vec{F}_{net} = m\vec{a}$
 $a_c = \frac{v^2}{r}$
 $f = \frac{1}{T}$
 $v = \frac{2\pi r}{T} = 2\pi r f$
 $T^2 = \text{constant} \times r^3$

$W = Fd \cos \theta$
 $K = \frac{1}{2}mv^2$
 $\Delta U = -W_c$
 $U = \frac{1}{2}kx^2$
 $U = mgh$
 $E = K + U$
 $\Delta E = \Delta K + \Delta U = 0$
 $W_{nc} = \Delta E = \Delta K + \Delta U$
 $W_{net} = \Delta K$
 $P_{av} = \frac{W}{t}$
 $P_{av} = Fv \cos \theta$
 $\vec{p} = m\vec{v}$
 $\Delta \vec{p}_1 = -\Delta \vec{p}_2$
 $\Delta \vec{p} = \vec{F} \Delta t$
 $\vec{F} = \frac{\Delta \vec{p}}{\Delta t}$
 Impulse = $\vec{F} \Delta t$
 $x_{cm} = \frac{m_1 x_1 + m_2 x_2 + \dots + m_n x_n}{m_1 + m_2 + \dots + m_n}$

$y_{cm} = \frac{m_1 y_1 + m_2 y_2 + \dots + m_n y_n}{m_1 + m_2 + \dots + m_n}$
 $\Sigma \vec{F}_{ext} = m\vec{a}_{cm}$

4 Kinematic equations for rotations:

- 1) $\omega = \omega_o + \alpha t$
- 2) $\theta = \theta_o + \frac{1}{2}(\omega + \omega_o)t$
- 3) $\theta = \theta_o + \omega_o t + \frac{1}{2}\alpha t^2$
- 4) $\omega^2 = \omega_o^2 + 2\alpha(\theta - \theta_o)$

$K_{rot} = \frac{1}{2}I\omega^2$
 $v = \omega r$
 $a_T = \alpha r$
 $I = \Sigma_{i=1}^N m r_i^2$
 $\tau = r F \sin(\theta)$
 $\Sigma \tau = I\alpha$

$$\Sigma \tau = \frac{\Delta L}{\Delta t}$$

$$K = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$$

$$L = I\omega$$

$$\rho = \frac{m}{V}$$

$$P = P_o + \rho gh$$

$$P = \frac{F}{A}$$

$$1 \text{ atm} = 1.013 \times 10^5 \text{ Pa}$$

$$\text{Pure water: } \rho = \frac{1g}{cm^3}$$

$$F_B = M_{fluid}g = \rho_{fluid}gV_{fluid}$$

$$A_1v_1 = A_2v_2$$

$$P_1 + 1/2\rho v_1^2 + \rho gy_1 = P_2 + 1/2\rho v_2^2 + \rho gy_2$$

$$\vec{v}_{ac} = \vec{v}_{ab} + \vec{v}_{bc}$$

$$T = 2\pi\sqrt{\frac{m}{k}}$$

$$x = A\cos(2\pi ft)$$

$$T = 2\pi\sqrt{\frac{L}{g}}$$

$$v = \lambda f$$

Moments of inertia of bodies about axes

